

by Fritz Ruoss

Spring programs: energy-mass ratio as indicator for efficiency and lightweight construction

In the spring programs a new factor is introduced: energy-mass-ratio (W_0/m) as indicator, how much energy can be stored with 1 kg of spring material. This allows you to compare different spring types, materials and cross-sectional shapes. Therefore, " W_0/m " is also included in the table under "File-> Open Table".

s1	s2	sn	sc	sh	sk	tauz/k	tauhz/l	cycl.M	t life	m [g]	w	Wn/m
10,27	18,65	22,06	24,84	8,38		0,72	0,19	0,0005	0,1	35	5,39	195
2,00	10,00	12,11	14,08	8,00	12,61	1,37	1,48	> 10	infinite	2	7,33	198
1,16	9,16	25,38	29,01	8,00		3,63	2,59	> 10	infinite	8	9,69	201
1,16	9,16	25,38	29,01	8,00		3,63	2,59	> 10	infinite	8	9,69	201
12,00	33,00	50,34	59,75	21,00	36,53	1,81	1,02	> 10	infinite	41	8,00	203
38,73	41,53	49,84	67,41	2,80	16,89	1,27	2,75	> 10	infinite	104	4,28	207
38,80	41,60	49,81	67,40	2,80	16,89	1,27	2,73	> 10	infinite	104	4,28	207
15,00	18,00	26,38	28,38	3,00		2,44				1	15,00	207
8,12	8,82	10,16	12,02	0,70	6,09	1,52	4,65	> 10	infinite	1	6,78	212
4,00	8,40	15,54	20,11	4,40	8,30		-0,32	0	0	14	4,75	212
12,00	26,00	71,81	77,69	14,00	27,14	1,61	0,96	7,6	2102	90	8,00	214
12,00	50,00	67,79	77,79	38,00	27,72	1,43	1,24	> 10	infinite	97	8,00	215
12,00	33,00	50,34	59,75	21,00	35,89	2,03	1,12	> 10	infinite	40	8,00	215
10,00	50,00	67,69	77,69	40,00	27,69	1,51	1,57	> 10	infinite	97	8,00	215
0,00	1,00	1,88	2,04	1,00		2,21	0,84			0	6,64	215
8,50	10,90	11,14	11,93	2,40		0,69	-1,34			9	6,03	216
12,00	24,00	71,13	77,79	12,00	27,77	3,48	2,04			98	8,00	216
2,90	7,95	8,46	9,99	5,05	2,05	1,45	1,14	> 10	infinite	0	6,80	217
7,00	17,00	21,15	23,44	10,00	21,00	1,73	0,96	7,0	1933	1	10,75	218
16,40	17,00	19,27	23,23	0,60	9,40	1,30	4,65	> 10	infinite	8	6,00	218
12,05	13,32	13,49	14,43	1,27		1,28	2,64	> 10	infinite	0	19,68	219
6,55	7,55	11,22	12,83	1,00		1,82	5,11	> 10	infinite	1	7,44	221
32,00	53,00	67,74	77,74	21,00	27,14	1,34	0,95	7	194	97	8,00	222

The energy-mass ratio also decreases for increasing wire diameters because the tensile strength decreases. At first glance it is also astonishing to compare a spiral spring with a leaf spring made from the same piece of steel strip. The compared spiral spring could store 10 times more energy than the unrolled leaf spring. This is because the bending stress in the spiral spring is distributed over all coils, whereas with a clamped leaf spring the highest bending stress occurs at the bearing position. On the other hand, a torsion bar spring has almost identical values compared to a helical compression spring, because torque and shear stress is constant over the entire length. The energy-mass ratio of rubber compression springs is surprisingly high. No wonder, because tensile pressure is distributed constant over the entire material volume. Metal springs are not practical in this form, cause spring travel is too small. But when using rubber springs as energy storage, hysteresis, relaxation and switching times should also be taken into account. In contrast, helical springs are applied to torsion, and torsion springs and leaf springs on bending. The highest stress occurs only on the external fibres. In the neutral fibre in the middle there is no tension at all (waste of material). With hollow wire one could improve the material utilization.

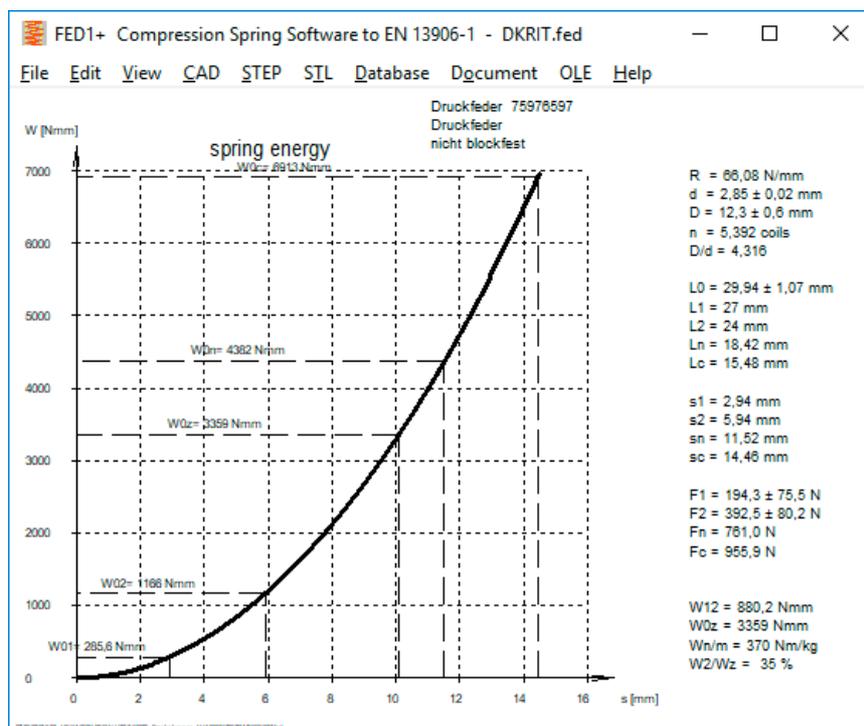
Spring Programs: spring energy efficiency

Another new degree of energy efficiency = $W02/W0n$ or $W02/W0z$ is used to indicate how much of the maximum usable energy of the spring will be used for the application. It should be noted that the degree of utilization can only be 100% for static applications, in case of dynamic application the (static) energy utilization factor must be less than 100%. For all springs except helical compression springs, disc springs and wave springs, the usable spring travel s_n and the usable spring energy W_n are limited by the permissible shear stress or permissible bending stress. In contrast, helical compression springs are usually designed block safe so that the permissible shear stress cannot be reached at all, because the spring is previously on block. For this case, a theoretical spring energy $W0z$ is calculated for helical compression springs, disc springs and wave springs, with theoretical maximum spring energy calculated from permissible shear stress or permissible bending stress.

spring energy between s_1 and s_2	W12	Nmm	186047
spring energy s_2	W02	Nmm	248063
spring energy s_n	W0n	Nmm	1699018
spring energy s_c	W0c	Nmm	2090832
spring energy τ_{auz}	W0z	Nmm	408125
spring energy $\min(s_n, \tau_{auz})$	Wn	Nmm	408125
energy efficiency	W02/W0z		61 %
energy-mass ratio	Wn/m	Nm/kg	257

FED1+: $F_n' = F(\tau_{auz})$, $W0z = f(\tau_{auz})$

In the case of springs, the index n stands for usable length L_n , usable spring force F_n , usable stress τ_{auz} = permissible stress τ_{auz} . In the case of compression springs, index n stands for the usable spring travel s_n = Block Length s_c – safety distance s_a . If the spring is not block resistant and the permissible shear stress is already exceeded at spring travel s_n , another usable spring force F_n' at the spring travel s_n' appears in the F-s diagram. For this case, the spring energy $W0z$ at spring travel s_n' has been added now, this means the usable spring energy until the permissible shear stress is reached.



FED2+ Quick Input

New Quick Input contains all input data integrated in only one large input window.

The old input windows (base data, text, material, production, tolerance, application, loops) remain available.

The screenshot shows the 'coiling direction' dialog box with the following details:

- Display:** Quick 3
- Aux. Image:** F1-D-105: Rm = f (d)
- Dimensions:** Recalculation selected. Input: De (Da) selected.
- Material:** 19: EN 10270-3-1.4568 X7CrNiAl17-7 17-7 PH
- Application:** type of stress: dynamic; required load cycles: 0; stress cycle frequency 1/s: 5; operating temperature T: 20 °C; external mass m: 0 kg.
- Production:** manufacturing depended pretension: spring coiler selected; input prestressing load F0: 7,346 N; input coiled-in prestress tau0: 95,27 MPa.
- Loops:** Loop 1 (upper) and Loop 2 (lower) both set to 'pic. A.2 (full german loop)'. Loop 2 = loop 1 is checked.
- Error Message:** Error: tau kh > tau h perm! S=0,99; Warning: tau kh !; Warning: Sig qh > sig hz S=0,69; Warning: T < T1relax (80°C).

FED2+: Get default loop height

In FED2 + there are also several special methods for dimensioning and recalculation of tension springs (online input). Under "Edit\Dimension" and "Edit\Recalculation" a suitable loop height (depending on the selected loop) is now suggested when you input LH1=0 or LH2=0.

The screenshot shows the 'FED2+ Recalculation' dialog box with the following details:

Input	Output
d: 1,2 mm	F1: 16,84 N
De: 10 mm	F2: 46,5 N
n: 10,000	R: 2,967 N/mm
LH1: 0 mm	Ln: 47,78 mm
LH2: 6,8 mm	tau k1: 259,7 MPa
F0: 7,346 N	tau k2: 717,3 MPa
L1: 30 mm	tau kh: 457,5 MPa
L2: 40 mm	tau perm902,5 MPa
T: 20 °C	L0: 26,8 mm
	s1: 3,2 mm
	s2: 13,2 mm

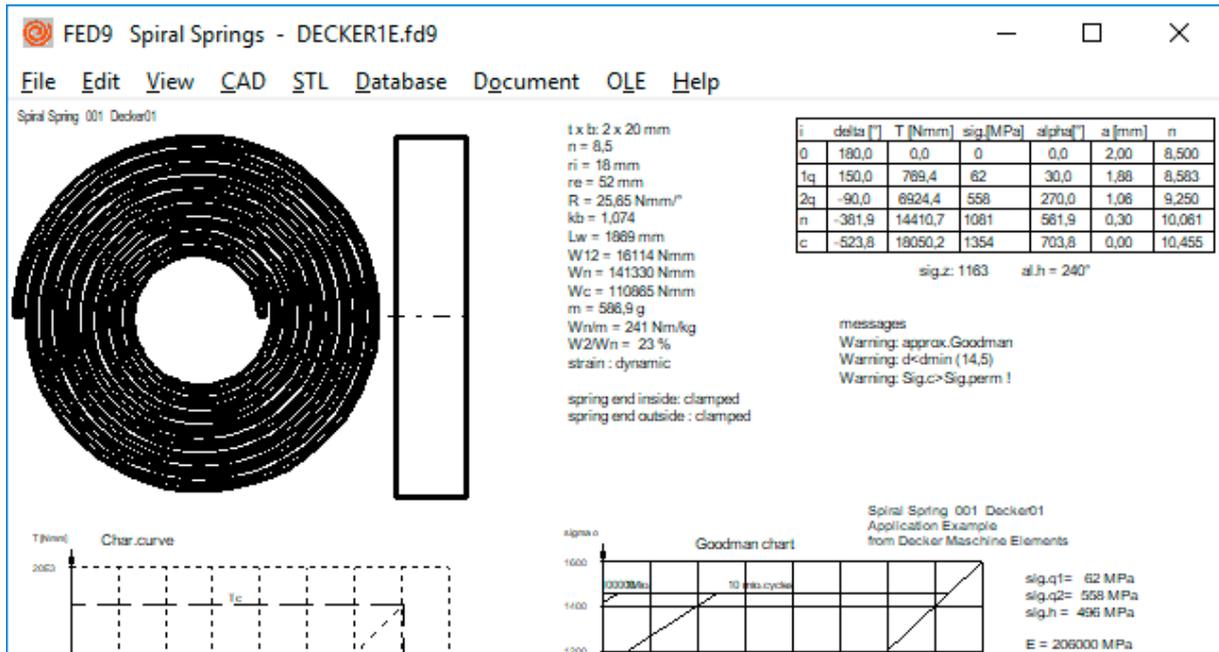
Error Messages: Error: tau kh > tau h perm! S=0,99; Warning: tau kh !; Warning: Sig qh > sig hz S=0,69; Warning: T < T1relax (80°C).

FED2 +: Torsional spring rate of extension springs

If the loops are twisted against each other, the tension spring is used like a torsion spring. For this case the torsional spring rate cm in Nmm/° is now calculated and printed.

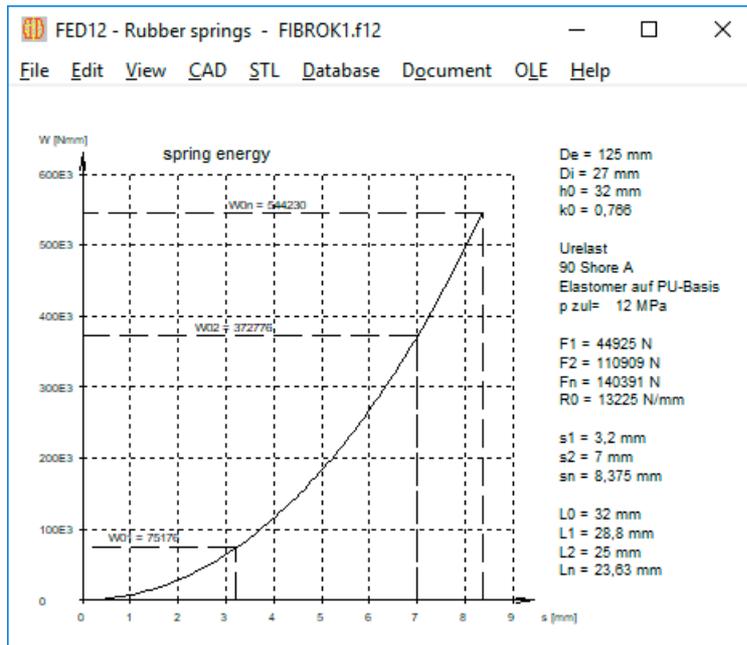
FED9: Usable spring travel of spiral springs

The usable spring travel is limited by the permissible bending stress. If the permissible bending stress is not exceeded even with full suspension on block, a safety distance S_a should be maintained, similar to the helical compression springs according to EN 13906. Since there is unfortunately no standard for spiral springs, in FED9 now similar to EN13906 " $S_a = n * 0.1 * d$ " or " $A_{min} = 0.1 * d$ " is set at static load. At dynamic load of warm-formed springs, S_a is doubled and with cold-coiled springs, S_a is 1.5-fold, analogous to EN 13906.



FED12: Spring Energy $W = f(s)$

New in FED12 for rubber springs is a diagram of the spring energy.



FED1+: Relaxation table

The relaxation table for working temperature and temperature limits in the $R_x = f(t)$ diagrams had been removed for some time, because the temperature and material-dependent calculation of the shear module in accordance with the current EN standard made the calculation more difficult. The relaxation table is now displayed again.

WN4,5,6,7,8,9,12, WNXE, WNXX, LG2: Production drawing in standardized scale

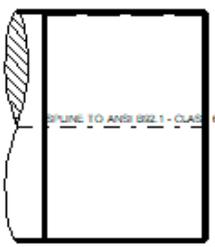
So far, a drawing of the calculated machine element has been fitted in an A4 sheet in maximum size. Now the drawing is inserted in the next smaller standard scale 1:1, 1:2, 1:5, 2:1, 5:1 etc.

WN4 - SAE Involute Splines - 85T ANSIB92 Class6.wn4

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HEXAGON WN4 - SAE Involute Splines V4.8

M 1:5



External Involute Spline Data	
SPLINE TO ANSI B92.1 - CLASS 6	
Fillet Root Side Fit	
Number of teeth	85
Spline pitch	10 / 20
Pressure angle	45 deg
Base diameter	6,010408 ref
Pitch diameter	8,500000 ref
Major diameter	8,592 / 8,600
Form diameter	8,423
Minor diameter	8,380 min
Circular tooth thickness	
Max effective	0,1771
Min actual	0,1704
Measurement over pins	
Max actual	8,9257
Min actual	8,9230
Pin Diameter	0,2362
Fillet Radius	0,021

Responsible dept.	Technical references	Created by	Approved by
Document type		Document status	
Title, Supplementary title			
Shaft			
Rev.	Date of issue	Lang.	Page
A	2018-06-28	en	

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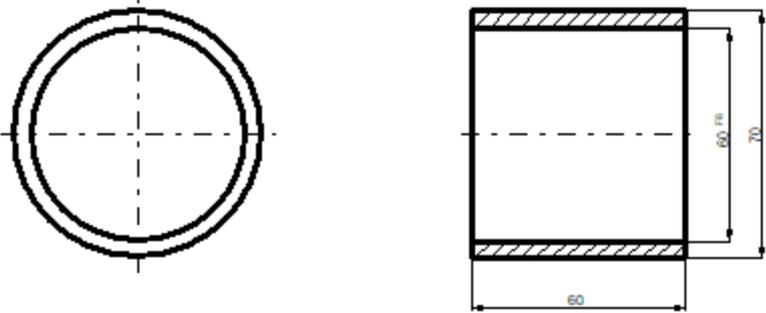
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LG2: Quick3 View and Quick4 View

New in LG2 are Quick3 View and Quick4 View with drawing of the journal bearing and tables with dimensions and calculation results altogether on one screen (print with Ctrl-P or File(Print))

LG2 - Hydrodynamic Plain Journal Bearings - DECKER1E.lg2

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Fit Dim.	Max.Dim.	Min.Dim.
60 F 8	60,076	60,030

Bearing 43164			
Example 17.1			
from Decker Maschinenelemente			

LIMITS			
max. specific bearing load	p lim	MPa	0,6
max. bearing temperature	tB lim	°C	90,0
low.adm.min. film thickness	h0 lim	mm	0,003

bearing			
bearing intem.diam.	D	mm	60 F8
bearing intem.diam.	Dmax	mm	60,076
bearing intem.diam.	Dmin	mm	60,030
thermal coefficient	al.1B	1/K	0,000022
bearing width, bearing	B	mm	60,00

shaft			
shaft diameter	d	mm	60 h6
shaft diameter	dmax	mm	60,000
shaft diameter	dmin	mm	59,981
thermal coefficient	al.1S	1/K	0,000011
rotational speed shaft	nS	1/s	5

lubricant: ISO VG 460			
density	rho	kg/m3	900
specific thermal capacity	c	J/(kgK)	2000
kinematic viscosity 40°C	v 40	mm²/s	460
kinematic viscosity 54°C	v eff	mm²/s	181,8
dynamic viscosity 40°C	eta 40	Pa s	0,414
dynamic viscosity 54°C	eta eff	Pa s	0,164

LG2			
bearing load	F	N	1000
specific bearing load	p	MPa	0,3
bearing clearance 20°C	s 20	mm	0,063
bearing clearance 54°C	s	mm	0,085
rel.bearing clearance 20°C	psi m		0,001042
rel.bearing clearance 54°C	psi eff		0,001416
Sommerfeld number	So		0,108
relative eccentricity	epsilon		0,089
film thickness min.	h0	mm	0,039
specific friction coefficient	psi/psi		30,005
friction coefficient	u		0,04250

heat removal: convection			
surface bearing case	A	m²	0,065
heat transfer coefficient	k	W/(m²K)	18
ambient temperature	ta	°C	20
bearing temperature	tB	°C	54,06
lubricant flow	Q	mm³/s	166,7
heat flow rate frictional energy	PO	W	40,05
ambient heat flow	PA	W	40,05

GEO4, ZAR4: Area, Area moment of inertia, center of gravity

For cams and noncircular gears, a table with area, area moments of inertia and coordinates of gravitation center has been added. Calculation and table are same as in GEO1.

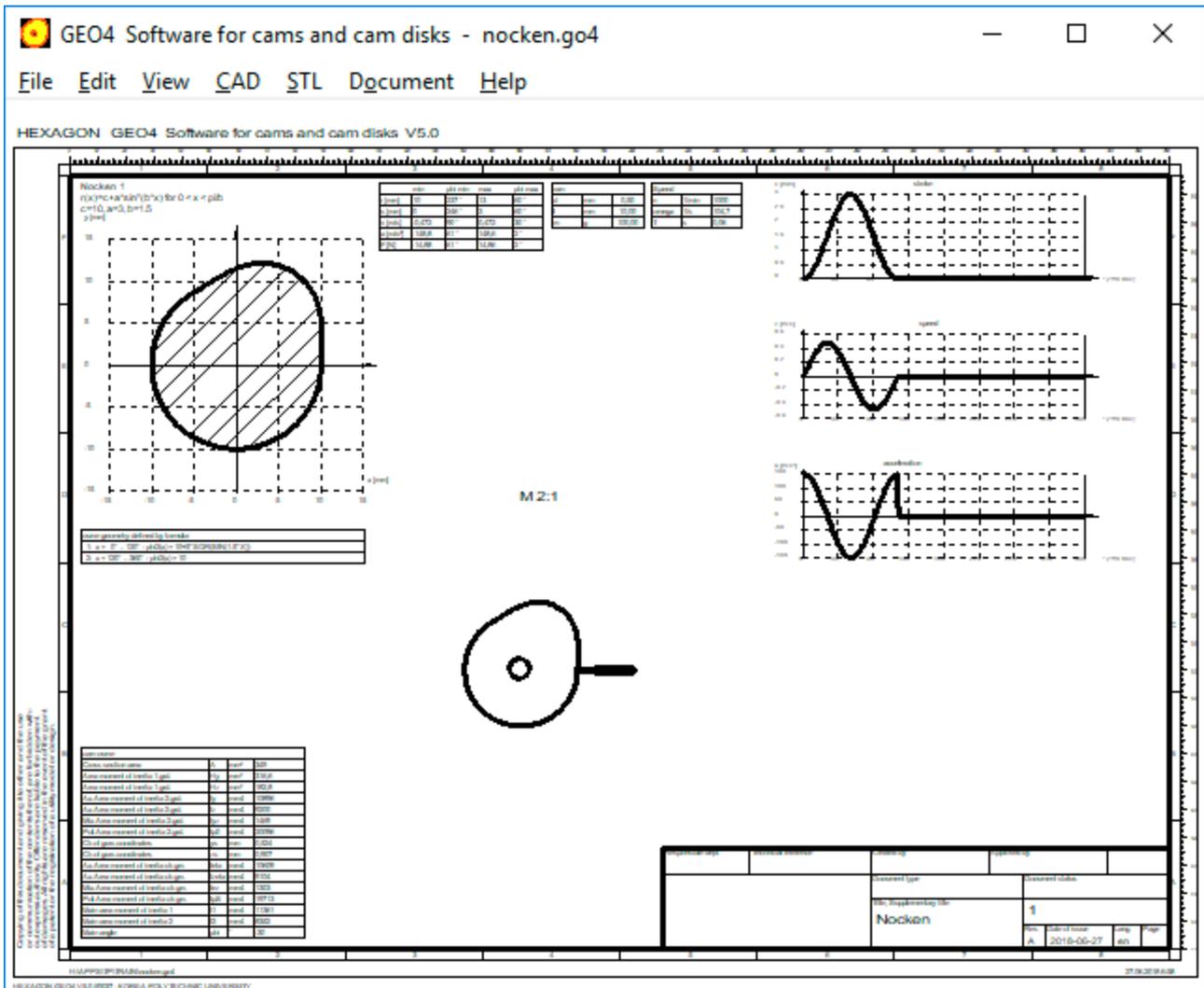
GEO4 Software for cams and cam disks - ...

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cam curve			
Cross section area	A	mm²	349
Area moment of inertia 1.grd.	Hy	mm²	316,6
Area moment of inertia 1.grd.	Hx	mm²	182,8
Ax.Area moment of inertia 2.grd.	Iy	mm4	10896
Ax.Area moment of inertia 2.grd.	Iz	mm4	9200
Mix.Area moment of inertia 2.grd.	Iyz	mm4	1469
Pol.Area moment of inertia 2.grd.	Ip0	mm4	20096
Ctr.of grav.coordinates	ys	mm	0,524
Ctr.of grav.coordinates	zs	mm	0,907
Ax.Area moment of inertia ctr.grv.	Ieta	mm4	10609
Ax.Area moment of inertia ctr.grv.	Izeta	mm4	9104
Mix.Area moment of inertia ctr.grv.	Iez	mm4	1303
Pol.Area moment of inertia ctr.grv.	IpS	mm4	19713
Main area moment of inertia 1	I1	mm4	11361
Main area moment of inertia 2	I2	mm4	8352
Main angle	phi	°	-30

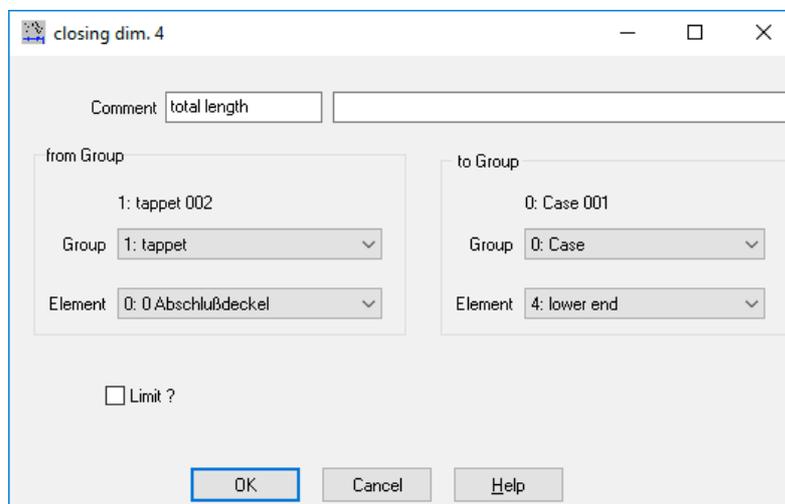
GEO4: Quick1, Quick3, Quick4 Views

New result screens Quick1, Quick3 and Quick4 with drawings, tables and diagrams of the calculated cams and cam shafts have been added to GEO4.



TOL2: Dialogue windows

There were error messages in the dialog boxes for entering groups and closing dimensions, and the TL1 file name was not displayed. If you get any errors in TOL2, please send a screenshot with the faulty dialog box, then you will receive a free update.



SR1: Thread strip safety

If standard screws and standard nuts of the same strength class are used, the thread strip safety must not be proven, because according to VDI 2230 no thread can be stripped down in this case. But if you choose and calculate the nut material, you will be amazed to find that you receive a warning about thread strip safety. In search of the cause, in PRESSURE.DBF database we modified shear stress ratio of the nut strength classes "QUAL12" to "QUAL3" according to the equivalent VDI2230 values of the bolt strength class "taub/Rm" to 0.6 and 0.7 (so far the value was 0.577 for all). But that's not enough yet. Safety factor increases, but remains below 1. Then you can still reduce the thread tolerances, ideally at 4h/4h. If this is still not enough, you could only reduce the non-bearing thread length of the chamfers. But then you will get a new warning "mzu < 2P".

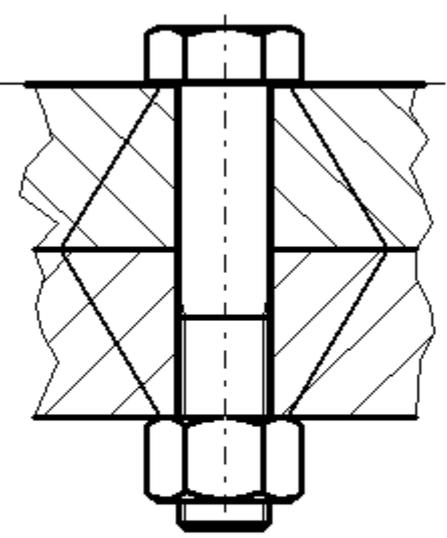
In the search for calculation examples, B2 from the VDI 2230 would be fine. A pity, under R11 stands only: "Omitted, since standardized nuts of a strength corresponding to the bolt are used."

SR1 calculates a minimum depth $m_{effmin} = 12 \text{ mm}$ using thread tolerance 6h/6g, but the bearing length of the nut is only $14.8 - 2 * P = 10.8 \text{ mm}$. The thread strip safety is then 0.9. According to VDI 2230, the minimum depth is calculated with tolerances for the worst case. The thread strip safety at R_{mmax} means that in case of overload the bolt breaks and does not strip the thread. If the load entered is not exceeded, the thread strip safety applies to $FM_{zul} + FSA$.

To represent the bandwidth of the minimum thread length of engagement m_{eff} at the highest and smallest tolerance, SR1 and SR1 + now also calculate the minimum length of engagement at the smallest thread tolerances and minimum tensile strength of the bolt. With example B2 from VDI 2230 you get a bandwidth of 12.0 mm to 7.8 mm for the minimum depth m_{effmin} , only by using min and max tolerance. This corresponds to a safety m_{tr}/m_{effmin} between 0.9 and 1.4.

SR1+ Bolted Joint Design to VDI 2230 - 2_2014.sr1
— □ ×

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ISO 4014 - M16 x 80 - 10.9 SW24						
i	de [mm]	di [mm]	l [mm]	A [mm²]	x [mm]	delta mm/N
1	16,00	0,00	42,00	201,1	42,00	0,995E-6
G3	13,51	0,00	18,00	143,3	60,00	0,598E-6
G2	14,66	0,00	20,00	168,9	80,00	

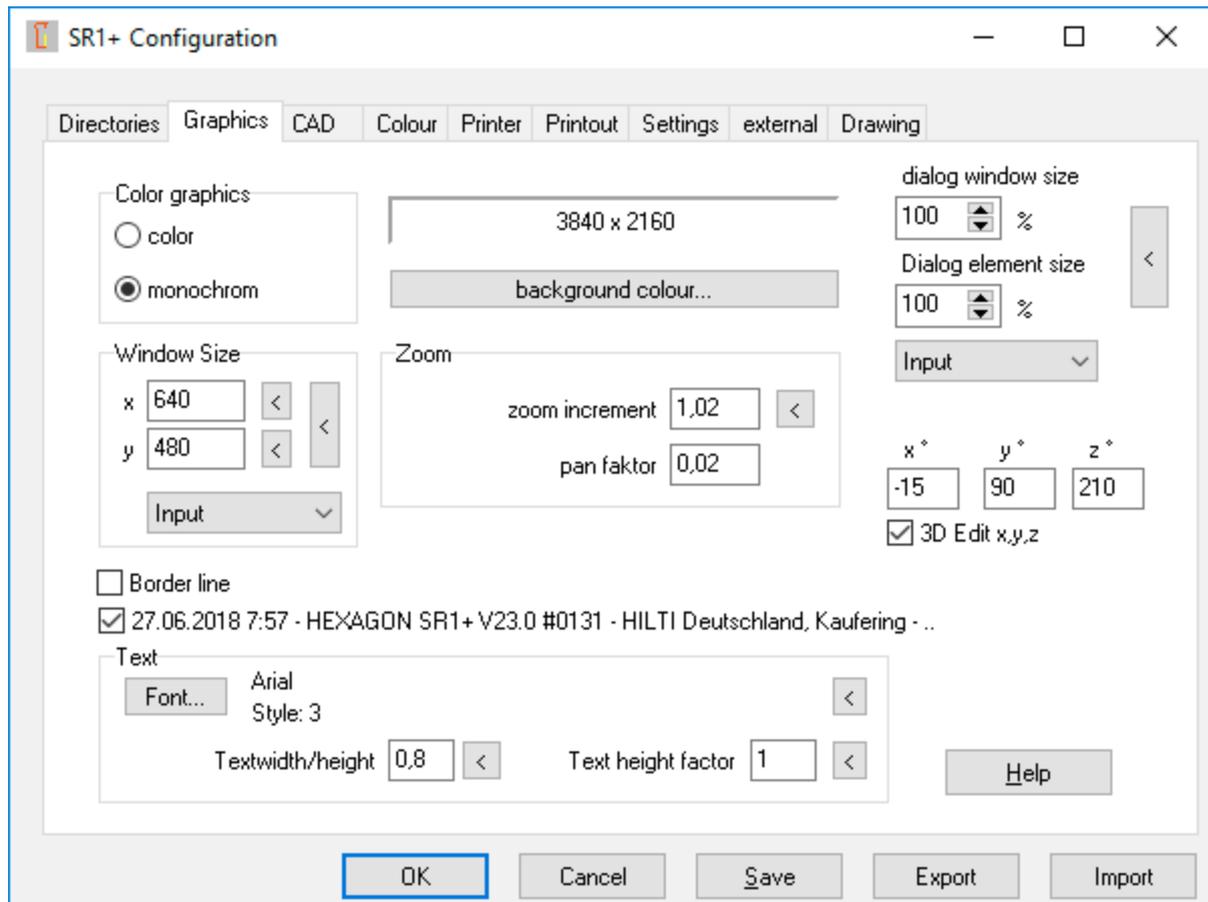
i	de [mm]	di [mm]	l [mm]	Name
1	99,0	17,7	0,4	Bohrungsfase
2	99,0	17,0	29,7	P 1
3	99,0	17,0	30,0	P 2

bolted joint with nut (TBJ)		
ISO 4032 - SW 24		
h M	mm	14,8
m tr = h M - 2,0 P	mm	10,8
m eff min Rm max/min VDI 2230	mm	12,0 / 7,8
m eff min FSmax VDI 2230	mm	8,8

Thread strip calculation factors C1, C2 and C3 of VDI 2230 have been added to the printout of SR1+ for proof and recalculation purpose.

Configure Dialog window and dialog elements

When large fonts or special dialog boxes are configured on Windows, the dialog boxes may be too large or too small. Then you have to configure "File\Settings\Graphics" "dialog window size" and appropriately "dialog element size". Default setting is 100% (first select "Input"). In previous versions you could drag the dialog box even bigger or smaller, but in newer versions there were mostly no scroll bars. So you had to configure the dialog window size correctly first. This change has now been reversed, so that even if the configuration is incorrect, you are not forced to cancel the calculation and to configure the dialog boxes first.



Comment about trade dispute and climate protection

Instead of responding to the US import duties on steel and aluminum with questionable "punitive tariffs" on whiskey, jeans, peanut butter and motorcycles, and thus to take off a customs avalanche, the EU should better appreciate import tariffs on steel and aluminium as an active contribution of the United States to global climate protection. Because it makes no sense to ship tons of steel and aluminum with high energy and pollutant emissions across land and across the oceans.

Also, the exit of Donald Trump from the climate change agreement is only honest: If I can't reach a goal, I'll admit that and leave it out. On the other hand, the other members of the climate change agreement are in breach of all climate protection goals, without any consequences. For the improvement of the carbon footprint of the exporting countries, the St-Al tariffs of the USA are helpful because the steel and aluminium production is extremely energy intensive.

And the level of US tariffs is not beyond the range: for bicycles from China, the European Union is raising a whopping 63.5% import duty (15% "normal" customs + 48.5% anti-dumping duty). That is why today in Europe you pay more money for a simple children's bike than for a four-stroke lawnmower with gasoline engine.

HEXAGON PRICELIST 2018-07-01

PRODUCT	EUR
DI1 Version 1.2 O-Ring Seal Software	190.-
DXF-Manager Version 9.1	383.-
DXFPLOT V 3.2	123.-
FED1+ V30.5 Helical Compression Springs incl. spring database, animation, relax., 3D,..	695.-
FED2+ V21.1 Helical Extension Springs incl. spring database, animation, relaxation, ...	675.-
FED3+ V19.4 Helical Torsion Springs incl. prod.drawing, animation, 3D, rectang.wire, ...	480.-
FED4 Version 7.6 Disk Springs	430.-
FED5 Version 16.0 Conical Compression Springs	741.-
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FED7 Version 13.6 Nonlinear Compression Springs	660.-
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FED17 Version 1.6 Magazine Spring	725.-
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GEO3 V3.3 Hertzian Pressure	205.-
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GEO5 V1.0 Geneva Drive Mechanism Software	218.-
GEO6 V1.0 Pinch Roll Overrunning Clutch Software	232.-
GR1 V2.1 Gear construction kit software	185.-
HPGL-Manager Version 9.1	383.-
LG1 V6.6 Roll-Contact Bearings	296.-
LG2 V3.0 Hydrodynamic Plain Journal Bearings	460.-
SR1 V23.0 Bolted Joint Design	640.-
SR1+ V23.0 Bolted Joint Design incl. Flange calculation	750.-
TOL1 V12.0 Tolerance Analysis	506.-
TOL2 Version 4.1 Tolerance Analysis	495.-
TOLPASS V4.1 Library for ISO tolerances	107.-
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WL1+ V21.2 Shaft Calculation incl. Roll-contact Bearings	945.-
WN1 Version 12.0 Cylindrical and Conical Press Fits	485.-
WN2 V10.1 Involute Splines to DIN 5480	250.-
WN2+ V10.1 Involute Splines to DIN 5480 and non-standard involute splines	380.-
WN3 V 5.4 Parallel Key Joints to DIN 6885, ANSI B17.1, DIN 6892	245.-
WN4 V 4.8 Involute Splines to ANSI B 92.1	276.-
WN5 V 4.8 Involute Splines to ISO 4156 and ANSI B 92.2 M	255.-
WN6 V 3.1 Polygon Profiles P3G to DIN 32711	180.-
WN7 V 3.1 Polygon Profiles P4C to DIN 32712	175.-
WN8 V 2.3 Serration to DIN 5481	195.-
WN9 V 2.3 Spline Shafts to DIN ISO 14	170.-
WN10 V 4.2 Involute Splines to DIN 5482	260.-
WN11 V 1.3 Woodruff Key Joints	240.-
WN12 V 1.1 Face Splines	256.-
WNXE V 2.2 Involute Splines - dimensions, graphic, measure	375.-
WNXK V 2.1 Serration Splines - dimensions, graphic, measure	230.-
WST1 V 10.2 Material Database	235.-
ZAR1+ V 26.3 Spur and Helical Gears	1115.-
ZAR2 V8.0 Spiral Bevel Gears to Klingelnberg	792.-
ZAR3+ V9.0 Cylindrical Worm Gears	620.-
ZAR4 V6.0 Non-circular Spur Gears	1610.-
ZAR5 V11.7 Planetary Gears	1355.-
ZAR6 V4.0 Straight/Helical/Spiral Bevel Gears	585.-

ZAR7 V1.5 Plus Planetary Gears	1380.-
ZAR8 V1.4 Ravigneaux Planetary Gears	1950.-
ZARXP V2.2 Involute Profiles - dimensions, graphic, measure	275.-
ZAR1W V2.1 Gear Wheel Dimensions, tolerances, measure	450.-
ZM1.V2.5 Chain Gear Design	326.-

PACKAGES	EUR
HEXAGON Mechanical Engineering Package (TOL1, ZAR1+, ZAR2, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WN2+, WN3, WST1, SR1+, FED1+, FED2+, FED3+, FED4, ZARXP, TOLPASS, LG1, DXFPLOT, GEO1+, TOL2, GEO2, GEO3, ZM1, WN6, WN7, LG2, FED12, FED13, WN8, WN9, WN11, DI1, FED15, WNXE, GR1)	8,500.-
HEXAGON Mechanical Engineering Base Package (ZAR1+, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WST1, SR1+, FED1+, FED2+, FED3+)	4,900.-
HEXAGON Spur Gear Package (ZAR1+ and ZAR5)	1,585.-
HEXAGON Planetary Gear Package (ZAR1+, ZAR5, ZAR7, ZAR8, GR1)	3,600.-
HEXAGON Involute Spline Package (WN2+, WN4, WN5, WN10, WNXE)	1,200.-
HEXAGON Graphic Package (DXF-Manager, HPGL-Manager, DXFPLOT)	741.-
HEXAGON Helical Spring Package (FED1+, FED2+, FED3+, FED5, FED6, FED7)	2,550.-
HEXAGON Complete Spring Package (FED1+, FED2+, FED3+, FED4, FED5, FED6, FED7, FED8, FED9, FED10, FED11, FED12, FED13, FED14, FED15, FED16, FED17)	4,985.-
HEXAGON Tolerance Package (TOL1, TOL1CON, TOL2, TOLPASS)	945.-
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- **German and English** : all Programs
- **French**: FED1+, FED2+, FED3+, FED4, FED5, FED6, FED7, FED9, FED10, FED13, FED14, FED15, TOL1, TOL2.
- **Italiano**: FED1+, FED2+, FED3+, FED4, FED5, FED6, FED7, FED9, FED13, FED14, FED17.
- **Swedish**: FED1+, FED2+, FED3+, FED5, FED6, FED7.
- **Portugues**: FED1+, FED17
- **Spanish**: FED1+, FED2+, FED3+, FED17

Updates:

Update prices	EUR
Software Update (software Win32/64 + pdf manual)	40.-
Software Update (software 64-bit Win + pdf manual)	50.-

Update Mechanical Engineering Package: 800 EUR, Update Complete Package: 1000 EUR

Maintenance contract for free updates: annual fee: 150 EUR + 40 EUR per program

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General packaging and postage costs for delivery on CD-ROM: EUR 60, (EUR 25 inside Europe)

Delivery by Email or download (zip file, manual as pdf files): EUR 0.

Conditions of payment: bank transfer in advance with 2% discount, or by credit card (Master, Visa) net.

Key Code

After installation, software has to be released by key code. Key codes will be sent after receipt of payment.

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